

## Advanced Calculus – Jacobians

/ is the division symbol

The mathematical modeling of complex existential problems often result in systems of partial differential equations. Several methods exist for determining the partial derivatives of such equations. The **Jacobian** is an effective method used to determine the partial derivatives of a system of partial differential equations, particularly when the number of equations are greater than two.

Consider the scenario with the following propositions:

(a)  $F(u, v, w, x, y, z), G(u, v, w, x, y, z), H(u, v, w, x, y, z), f(x, y, z), g(x, y, z), h(x, y, z) \in C^1$

(b)  $F(f(x, y, z), g(x, y, z), h(x, y, z), x, y, z) \equiv 0$

(c)  $G(f(x, y, z), g(x, y, z), h(x, y, z), x, y, z) \equiv 0$

(d)  $H(f(x, y, z), g(x, y, z), h(x, y, z), x, y, z) \equiv 0$

Then there exist, the **Jacobians** of F, G, H with respect to any subset of the variables of F, G, and H. For example, the Jacobian of F, G, H with respect to u, v, x is as follows:

$$\delta(F, G, H) / \delta(u, v, x) = \begin{vmatrix} F_1 & G_1 & H_1 \\ F_2 & G_2 & H_2 \\ F_4 & G_4 & H_4 \end{vmatrix}$$

Note how positions of the variables in F, G, and H is reflected in the partial derivatives in determinant .

And,  $\delta u / \delta x = - [\delta(F, G, H) / \delta(u, v, x)] / [\delta(F, G, H) / \delta(u, v, w)]; \quad \delta(F, G, H) / \delta(u, v, w) \neq 0.$

Other partial derivatives implicit in F, G, H can be similarly determined via their respective Jacobians.

**(1)** Determine  $\delta(F, G, H) / \delta(u, w, v)$ , If:

$$F = xu + v - y$$

$$G = u^2 + vy + w$$

$$H = zu - v + vw$$

**Ans (1)**

$$\delta(F, G, H) / \delta(u, w, v) = \begin{vmatrix} F_1 & G_1 & H_1 \\ F_3 & G_3 & H_3 \\ F_2 & G_2 & H_2 \end{vmatrix} = \begin{vmatrix} x & 2u & z \\ 0 & 1 & v \\ 1 & y & w-1 \end{vmatrix} = x(w-1-yv) - 2u(-v) + z(-1)$$

$$= xw - x - xyv + 2uv - z = 2uv + xw - x - xyv - z.$$

**(2)** Find  $\delta u / \delta x, \delta u / \delta y$  by use of Jacobians If  $u = f(u, v, x) \quad v = g(u, v, y)$

**Ans (2)** Set  $F(u, v, x, y) = u - f(u, v, x); G(u, v, x, y) = v - g(u, v, y)$

So,  $\delta u / \delta x = - [\delta(F, G) / \delta(x, v)] / [\delta(F, G) / \delta(u, v)] = f_3(1-g_2) / [(1-f_1)(1-g_2) - f_2g_1]$

So,  $\delta u / \delta y = - [\delta(F, G) / \delta(y, v)] / [\delta(F, G) / \delta(u, v)] = f_2g_3 / [(1-f_1)(1-g_2) - f_2g_1].$

## Advanced Calculus – Jacobians

**(3)** If  $F(x, y, u) = 0$ , is  $\delta u / \delta x$  equal to the reciprocal of  $\delta x / \delta u$  ?

**Ans (3)**  $\delta u / \delta x = -(\delta F / \delta x) / (\delta F / \delta u) = -F_1/F_3$

$\delta x / \delta u = -(\delta F / \delta u) / (\delta F / \delta x) = -F_3/F_1$

So, yes  $\delta u / \delta x =$  reciprocal of  $\delta x / \delta u$ .

**(4)** If  $F(x, y, u, v) = 0, G(x, y, u, v) = 0$ , is  $\delta u / \delta x$  equal to the reciprocal of  $\delta x / \delta u$  ?

**Ans (4)**  $u, v$  as dependent variable:

$\delta u / \delta x = -(\delta(F, G) / \delta(x, v)) / (\delta(F, G) / \delta(u, v)) = - (F_1G_4 - F_4G_1) / (F_3G_4 - F_4G_3)$

$x, y$  as dependent variable:

$\delta x / \delta u = -(\delta(F, G) / \delta(u, y)) / (\delta(F, G) / \delta(x, y)) = - (F_3G_2 - F_2G_3) / (F_1G_2 - F_2G_1)$

So, No  $\delta u / \delta x \neq$  reciprocal of  $\delta x / \delta u$ .

**(5)** Find the derivative of  $u$  with respect to  $x$  if

$$xu + uv = u - x$$

$$v^2 + xv = u + x$$

Is the derivative total or partial ?

**Ans (5)** Set  $F(u, v, x) = xu + uv - u + x = 0$

$G(u, v, x) = v^2 + xv - u + x = 0$

Then,  $du/dx = -(\delta(F, G) / \delta(x, v)) / (\delta(F, G) / \delta(u, v)) \quad (\delta(F, G) / \delta(u, v)) \neq 0$

$dv/dx = -(\delta(F, G) / \delta(v, x)) / (\delta(F, G) / \delta(u, v))$

So,  $du/dx = - (F_3G_2 - F_2G_3) / (F_1G_2 - F_2G_1)$

$= -[(u + 1)(2v + x) - u(v + 1)] / [(x + v - 1)(2v + x) - u(-1)].$

Derivative is total since there is a single independent variable.

**(6)** If  $F(u, v, g(u, v, x)) = 0$  and  $G(u, v, h(u, v, x)) = 0$ ; Find  $\delta u / \delta x$ .

**Ans (6)**  $\delta(F, G) / \delta(x, v) = \begin{vmatrix} F_3g_3 & G_3h_3 \\ F_2 + F_3g_2 & G_2 + G_3h_2 \end{vmatrix} = [F_3g_3(G_2 + G_3h_2) - G_3h_3(F_2 + F_3g_2)]$

$\delta(F, G) / \delta(u, v) = \begin{vmatrix} F_1 + F_3g_1 & G_1 + G_3h_1 \\ F_2 + F_3g_2 & G_2 + G_3h_2 \end{vmatrix} = [(F_1 + F_3g_1)(G_2 + G_3h_2) - (F_2 + F_3g_2)(G_1 + G_3h_1)] \neq 0$

So,  $\delta u / \delta x = -(\delta(F, G) / \delta(x, v)) / (\delta(F, G) / \delta(u, v))$

$= -[F_3g_3(G_2 + G_3h_2) - G_3h_3(F_2 + F_3g_2)] / [(F_1 + F_3g_1)(G_2 + G_3h_2) - (F_2 + F_3g_2)(G_1 + G_3h_1)].$

Peter Oye Simate Sagay  
 Simate was my mother  
 Sagay was my father